HYBRID CO-SIMULATION OF FMUs USING DEV&DESS IN MECSYCO

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SIMULATION CHALLENGES OF SMART GRIDS



FMI 2.0 : PRESENTATION

FMI, a standard for Model Exchange & Co-Simulation



Models are managed by time-stepped solvers

Solution preferred by EDF





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Based on a communication points execution strategy

Basic computation functions to:

- perform an integration to a given time-step (fmi2DoStep)
- set inputs' values (fmi2SetReal/Integer/Boolean/String)
- get outputs' values (fmi2GetReal/Integer/Boolean/String)

Optional functions enabling to export/import the model state

fmi2GetFMUState / fmi2SetFMUState

→Essential to enable roll-back, i.e. go a single integration step back

Many more functions available in the FMI API...

FMI 2.0: LIMITATIONS FOR STATE EVENTS

Hybrid co-simulation : FMU must interact with event-based model

- We must integrate input events into an FMU,
- and manage the generation of state-event from an FMU

Exact detection of occurrence times is difficult

- State-changes are not tagged: No persistent variable to inform if (when) an event occurred during a simulation step
- Bias when event (states or input) occurs between two communication points
 - state events are localized at the upper communication point
 - new inputs are integrated at the upper communication point



DEV&DESS:

- offers a sound framework for formalizing how an equation based component interacts with the discrete-world.
- embedded by Zeigler in DEVS which is a universal formalism for describing discrete-event models
- ➔ If it is wrapped into DEV&DESS, an FMU can interact with discreteevent models.

Issues:

- the original DEVS version of DEV&DESS relies on a quantized integrator approach
- Not compliant with the time-stepped framework of FMI for co-simulation
- → We need to adapt the original DEVS version of DEV&DESS

DEV&DESS WRAPPER ARCHITECTURE

Continuous component = the FMU to integrate

Discrete-event component = the discrete behavior of the FMU – i.e. :

- How the FMU state changes when events occurs?
- What are the output event produced by the model?

Event-detection component – i.e. :

Is there a state-event according to the FMU state?

The Time of the Next Internal Event is the minimum between:

- the date of the next internal event scheduled in the discrete event component Trivi
- the date of the next communication point of the FMU
- the date of the next state-event } Not known a priori

getNextInternalEventTime() must not change the state of the model

Thus, we :

- Perform a time exploration with the FMU to see if a state-event occurs before its next communication point
- Use its rollback capability to restore the state of the FMU before the exploration, if required

STATE EVENT LOCALIZATION STRATEGY

Bisectional search for state-event localization

```
INPUT: \Delta T \in \mathbb{R}^+_0, m \in \mathbb{N}^+_0
 \delta t \leftarrow 0
 \Delta t \leftarrow \Delta T
 for 1 to m do
      solver.rollBack()
      \Delta t \leftarrow \Delta t/2
      solver.doStep(\delta t + \Delta t)
      if \neg detFunction.stateEventOccurence() then
           \delta t \leftarrow \delta t + \Delta t
      end if
 end for
                                                                                            If event detected, rollback &
                                                                                            Dt_{i+1} = max(min step, Dt_i/2)
                         Event
                                               Event
 true
                                                                                      true
                                            detection
false
                                                                                    false
         ti
               Original step size
                                           t<sub>i+dt</sub>
                                                                                             ti
```

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processExternalEvent reports the occurrence of an external input event at *t*

- 1. The FMU is rolled back to its previous state
- 2. A new simulation step to *t* is computed to reach the point where the event occurs (no new event will occur in the meanwhile)

processInternalEvent works similarly

- But, the FMU state after the exploration is reused if the internal event time is the same
- This limits the computational burden of the exploration method

MECSYCO

Co-simulation middleware Using a DEVS wrapping strategy

1 wrapper = 1 model/simulator

Based on Agent & Artifact (A&A) concepts :

- Autonomous agents
- Passive artifacts proposing services to Agents

Advantages for co-simulation :

- Multi-representation integration (e.g. multi-level modeling)
- Multi-formalism integration (thanks to DEVS)
- Simulators interoperability (e.g. NS-3, OMNeT++, NetLogo, ad-hoc)
- Modular view
- Parallel & decentralized execution
- thanks to the multi-agent paradigm

Distributable architecture

STUDIED USE CASE: A BARREL FACTORY

A simple use case to illustrate the generic aspect of our methodology:

applicable outside from the context of Smart Grids



A fully implemented and functional wrapper for integrating FMU 2.0 components into a hybrid co-simulation was developed



STUDIED USE CASE: MODELING



RESULTS

Outputs of the continuous and discrete components



Taking simultaneously account of continuous and discrete dynamics within the FMU components.

Accuracy of the state event detection

	step size	$t_{barrel1}$	$t_{barrel2}$	$t_{barrel3}$	$t_{barrel4}$	$t_{barrel5}$	$t_{barrel6}$	$t_{barrel7}$	$t_{barrel8}$	$t_{barrel9}$
s 1	0.001	1.016	1.613	1.910	2.715	5.773	7.342	8.535	10.412	15.139
rie	0.01	1.016	1.613	1.910	2.715	5.773	7.342	8.535	10.412	15.139
Sei	0.1	1.016	1.613	1.910	2.715	5.773	7.342	8.535	10.412	15.139
s2	0.001	1.017	1.615	1.910	2.716	5.774	7.344	8.538	10.419	15.167
rie	0.01	1.020	1.620	1.900	2.710	5.770	7.340	8.540	10.430	15.230
Sei	0.1	1.100	1.800	1.800	2.600	5.700	7.300	8.500	10.400	15.300

Series 1 : proposed implementation of the DEV&DESS model artifact **Series 2** : classic FMU co-simulation strategy with constant time step

Bisectional search = same accuracy, independently of the step size

CONCLUSIONS AND PERSPECTIVES

A fully functional and generic wrapper for integrating FMU 2.0 components into a hybrid co-simulation

- Respects the DEV&DESS semantics and the FMI 2.0 operational constraints
- Rigorous interactions of FMU and event-based models within DEVS framework

Further improvements of the event location strategy:

Illinois algorithm or a combination of other existing algorithms are considered.

A solution applied to large Smart Grids and Smart Spaces

 Large use cases involving several domains are being considered, among which: electric systems, telecom systems, thermal systems and information systems



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